

Fig. 2

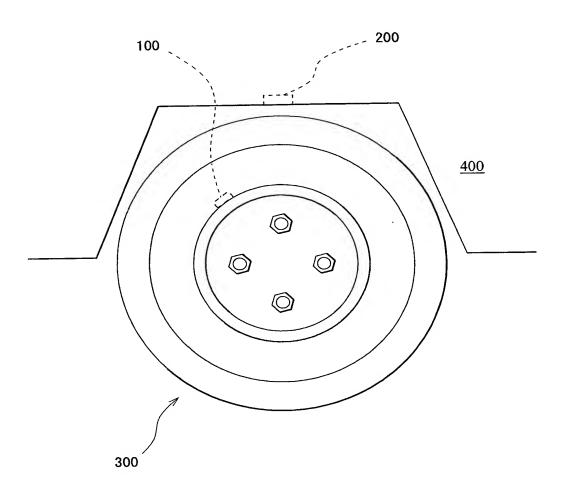


Fig. 3

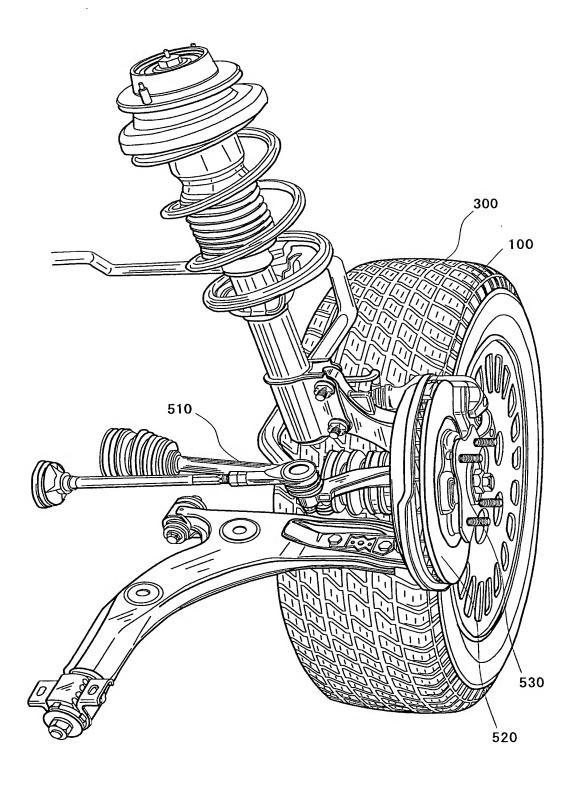
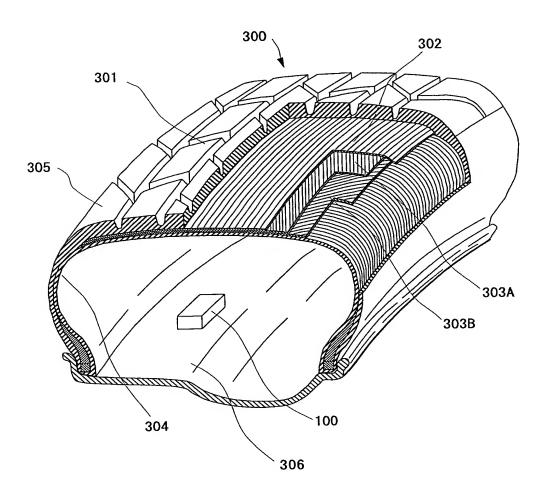


Fig. 4



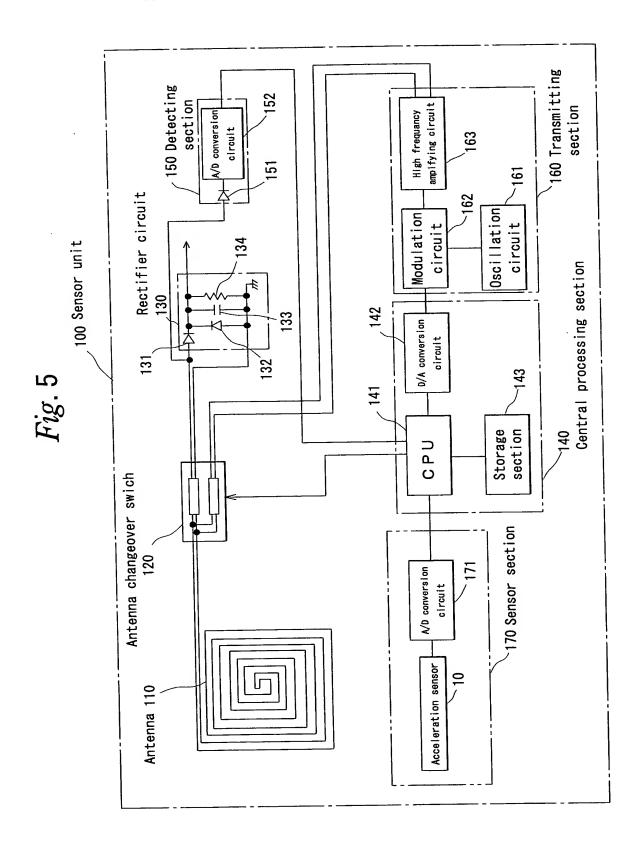


Fig. 6

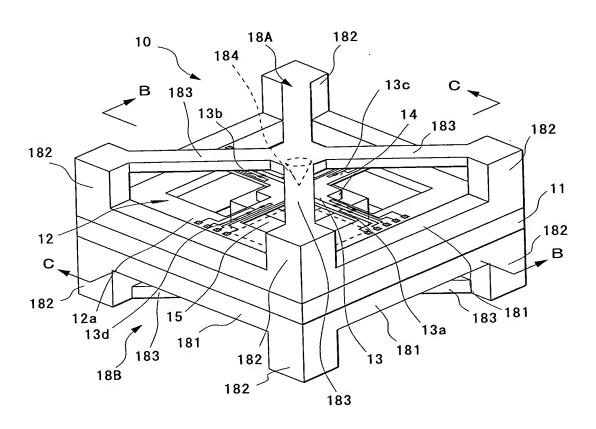


Fig. 7

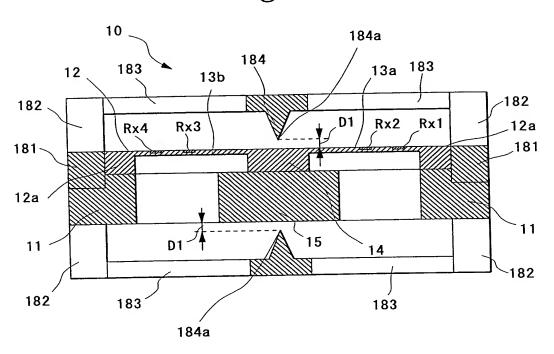
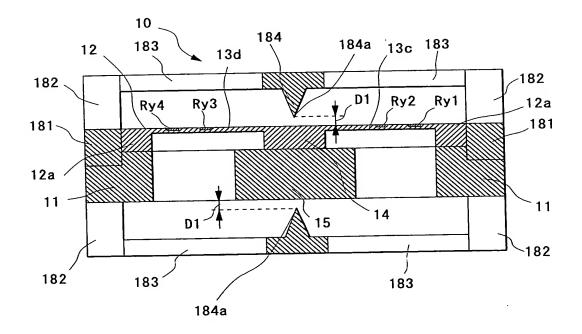


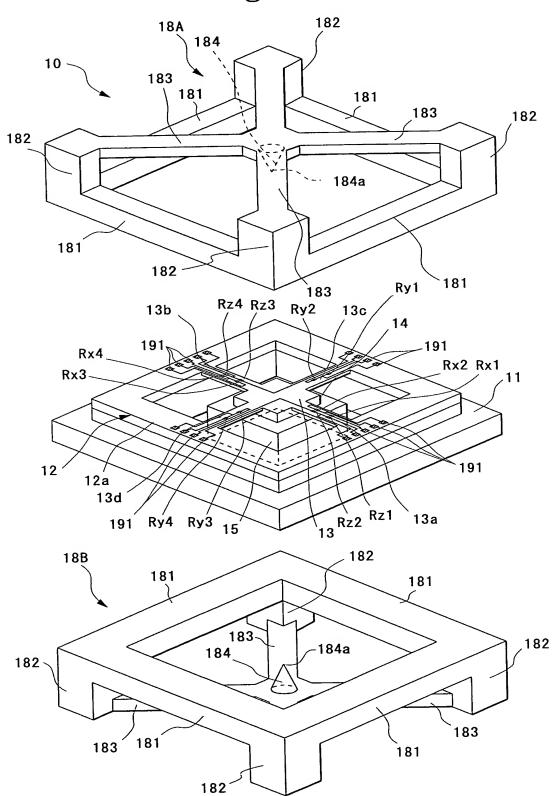
Fig. 8



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Fig. 9



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Fig. 10

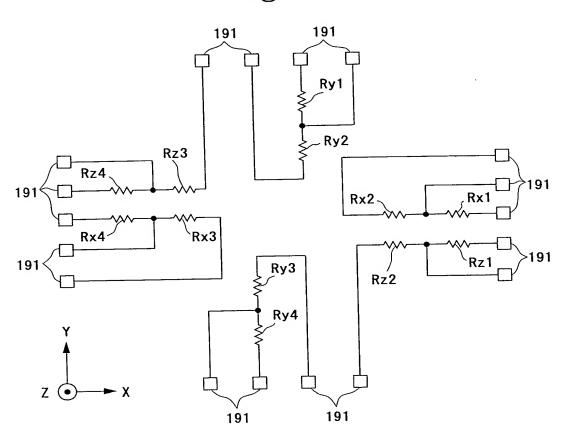


Fig. 11

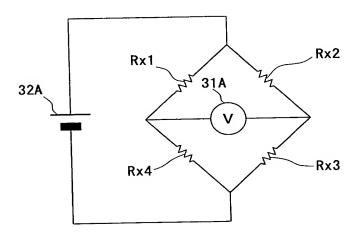


Fig. 12

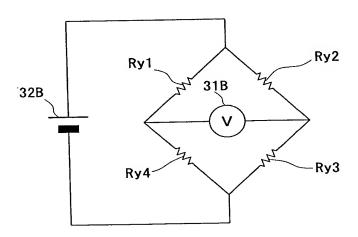
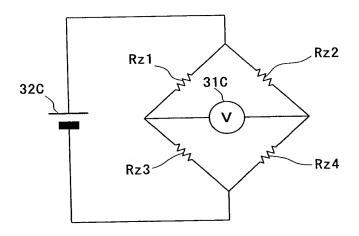


Fig. 13



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Fig. 14

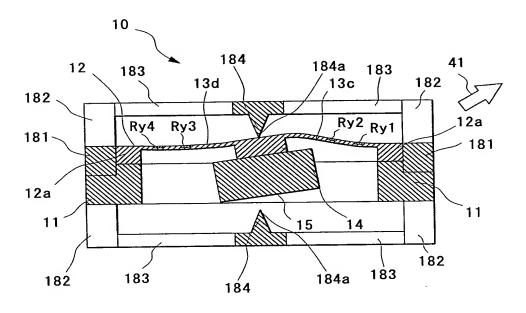


Fig. 15

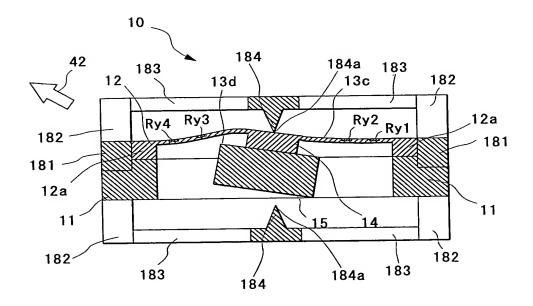
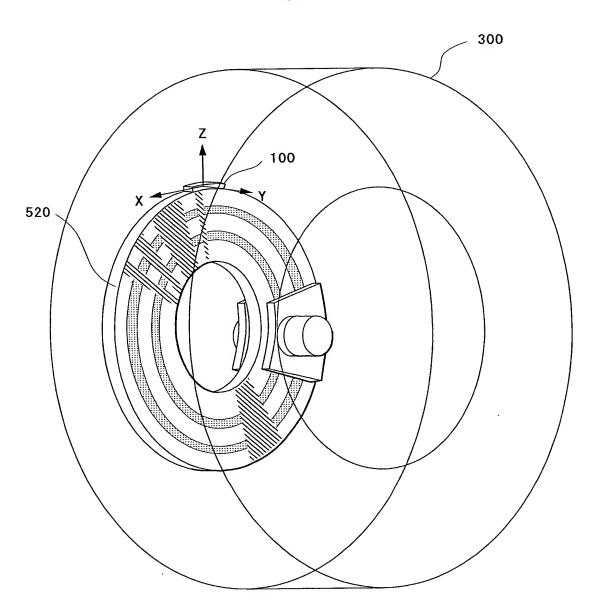


Fig. 16



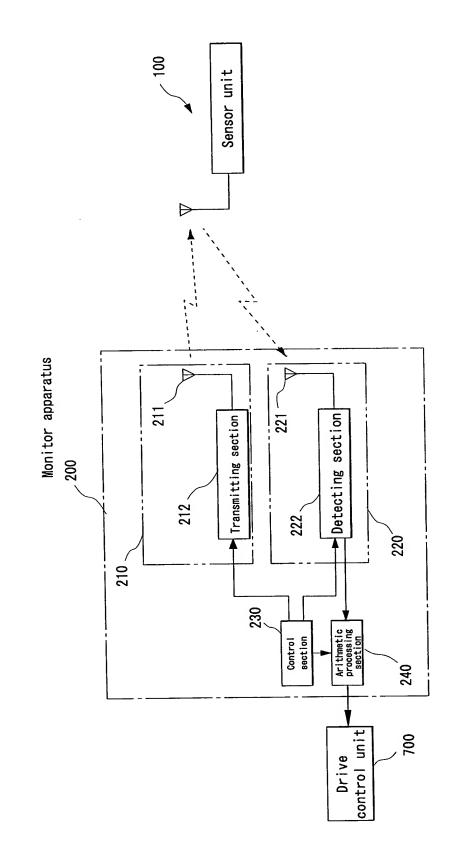
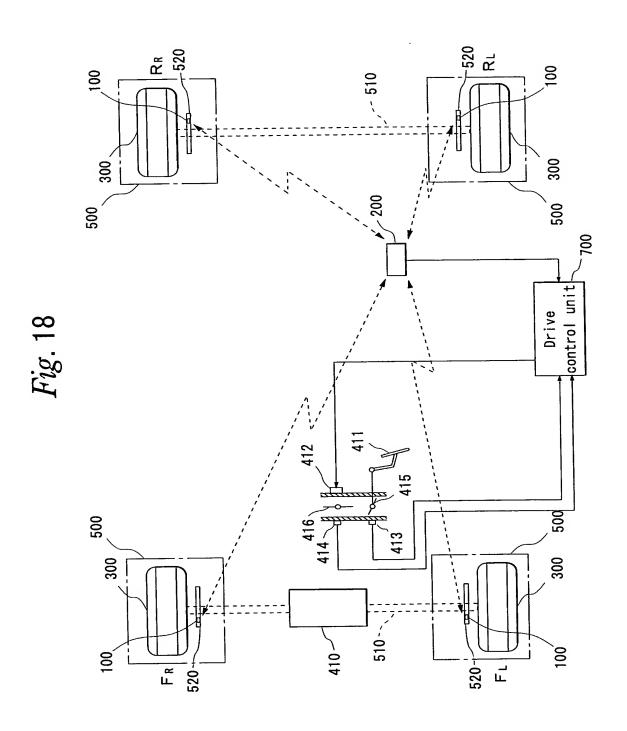


Fig. 17



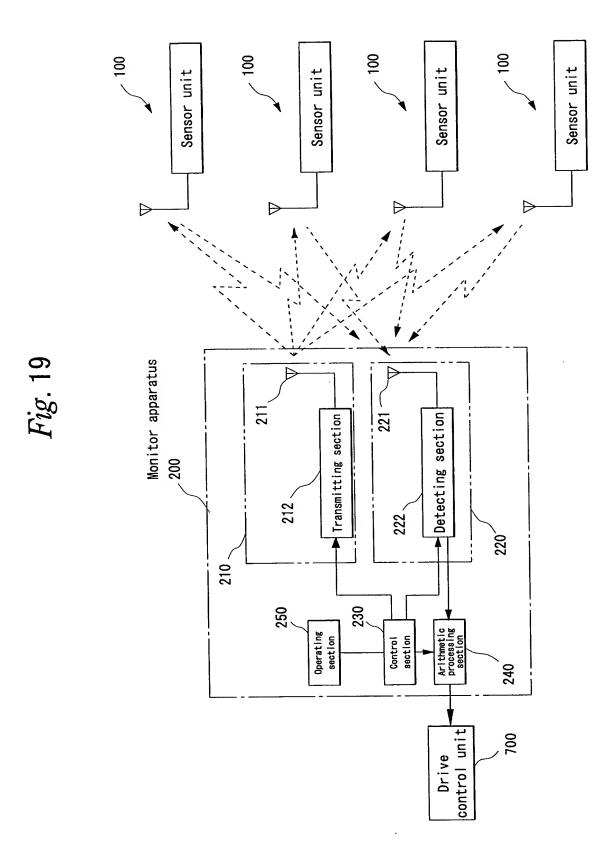


Fig. 20

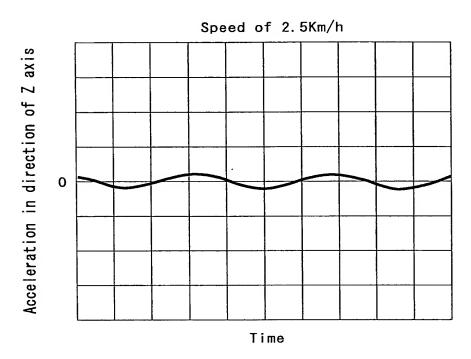
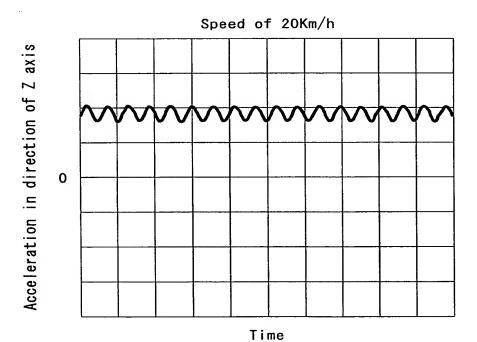


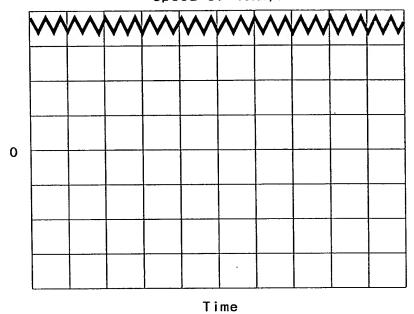
Fig. 21



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Fig. 22

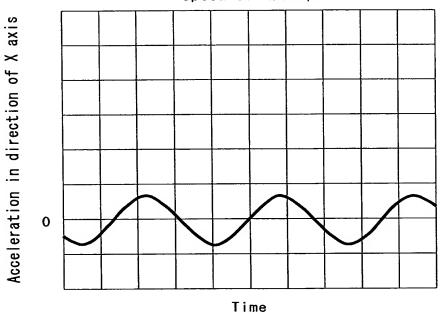
Speed of 40Km/h



Acceleration in direction of Z axis

Fig. 23

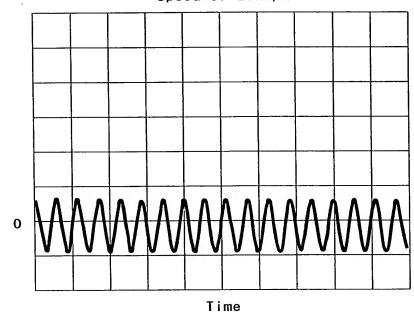
Speed of 2.5Km/h



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Fig. 24

Speed of 20Km/h



Acceleration in direction of X axis

Fig. 25

Speed of 40Km/h

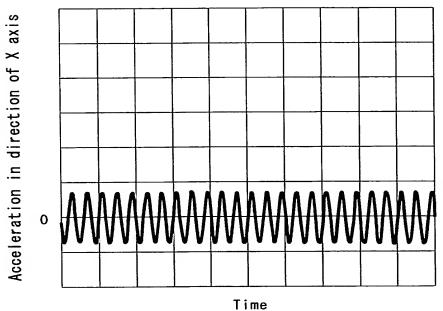


Fig. 26

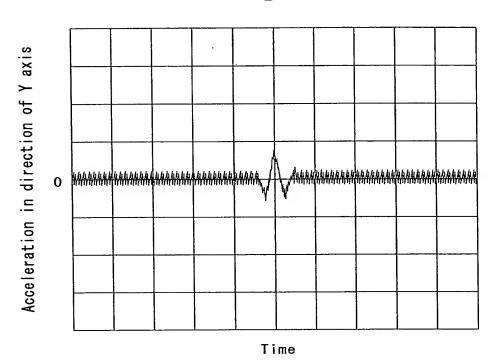


Fig. 27

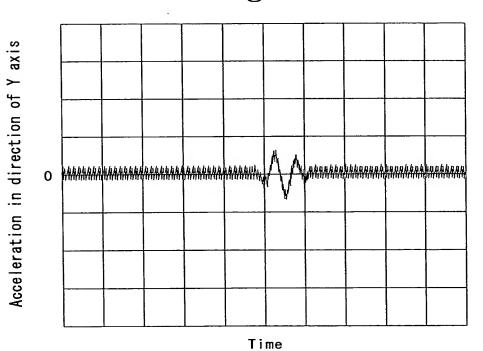


Fig. 28

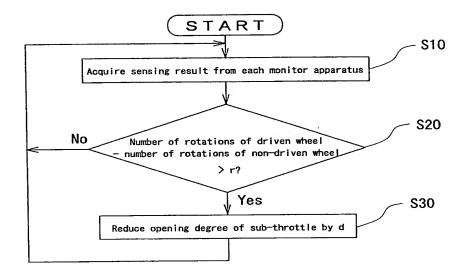
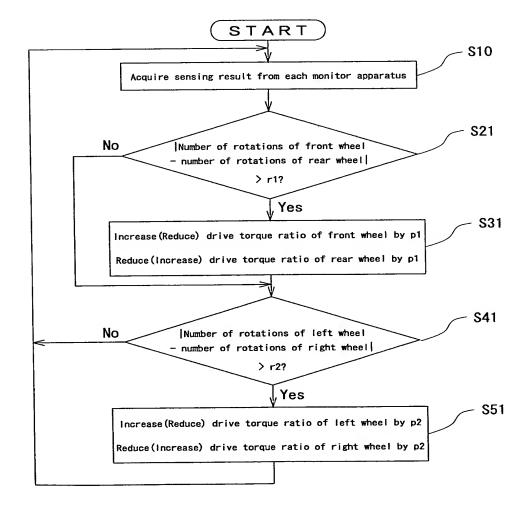
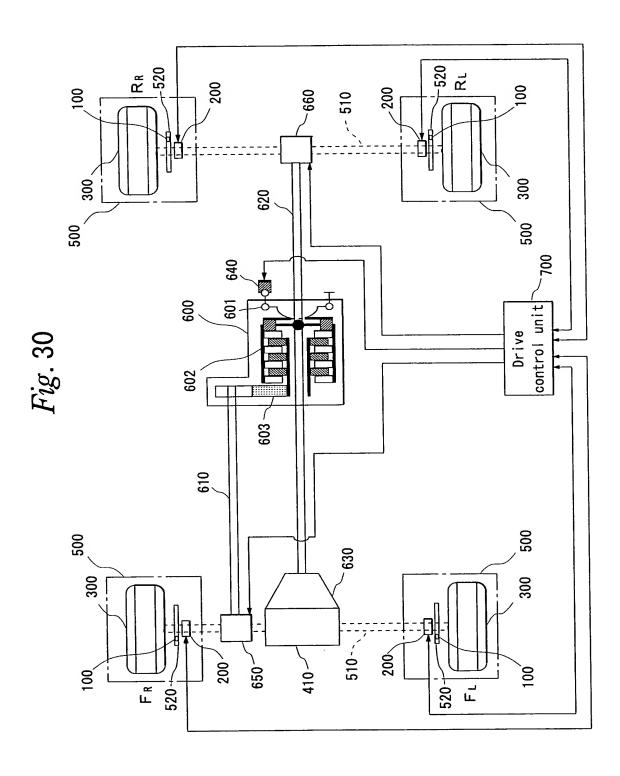


Fig. 29





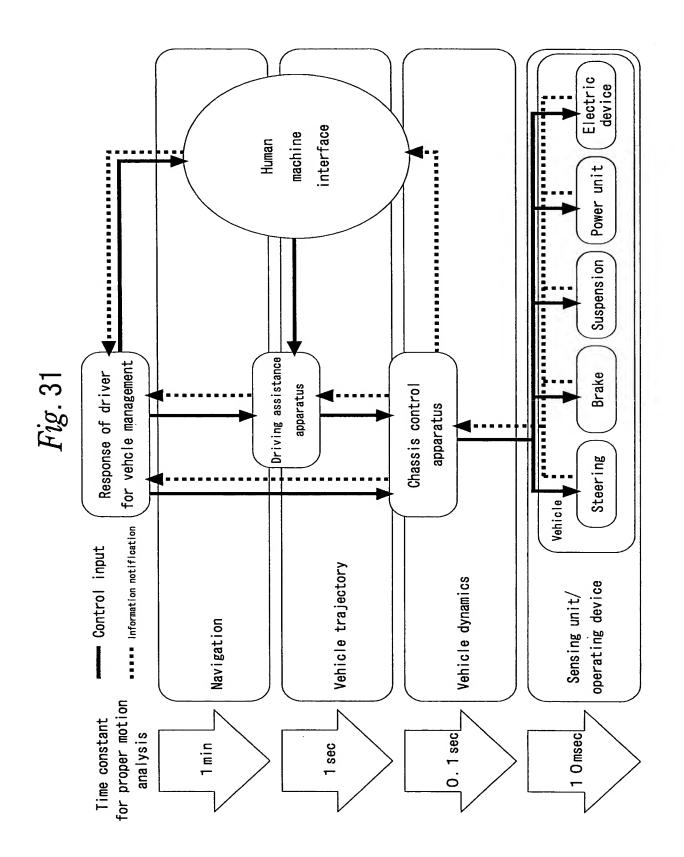


Fig. 32

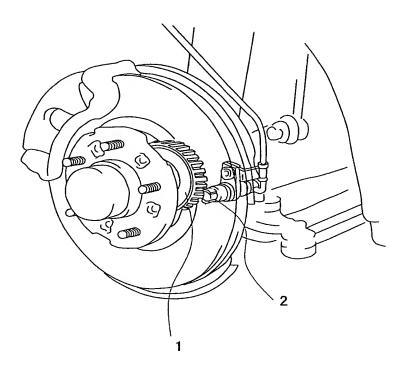


Fig. 33

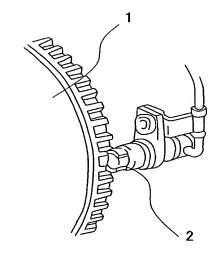
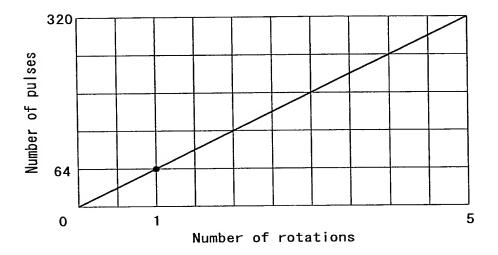
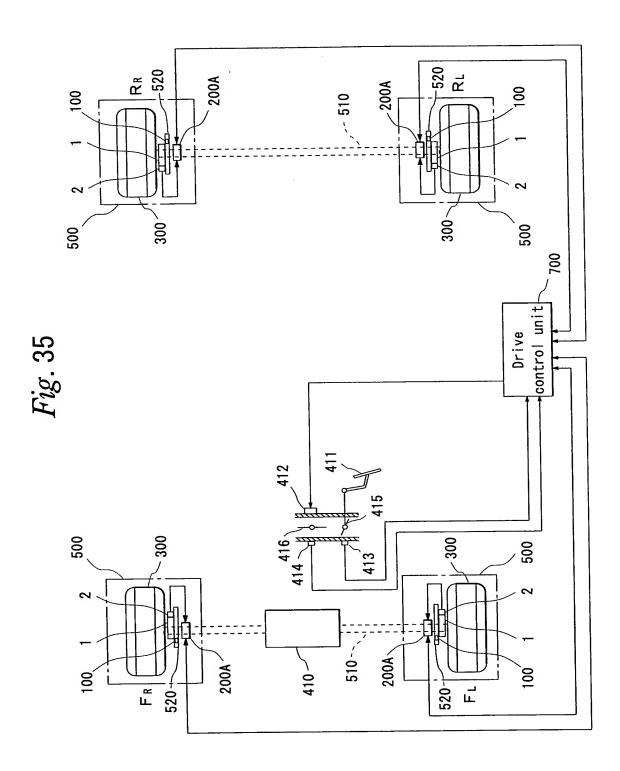


Fig. 34





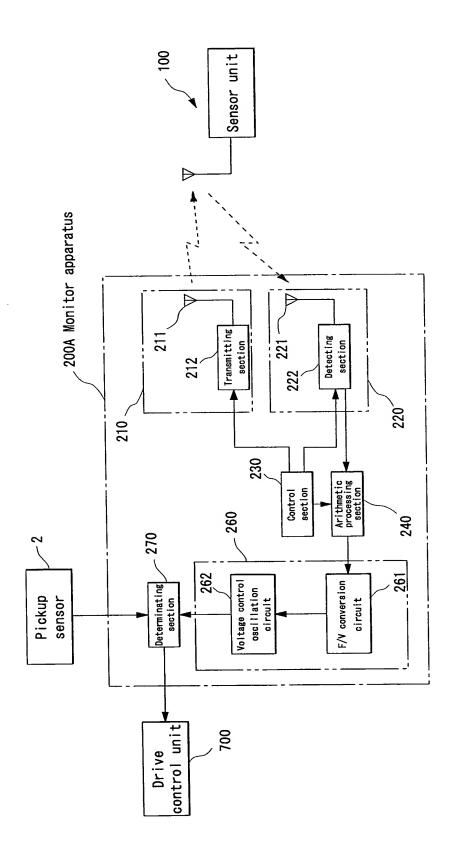


Fig. 36

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Fig. 37

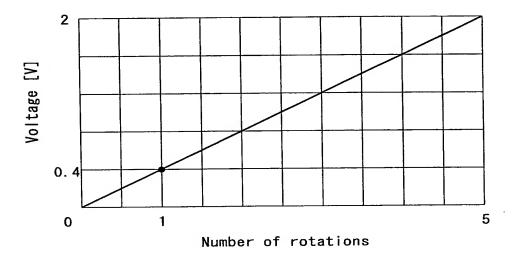
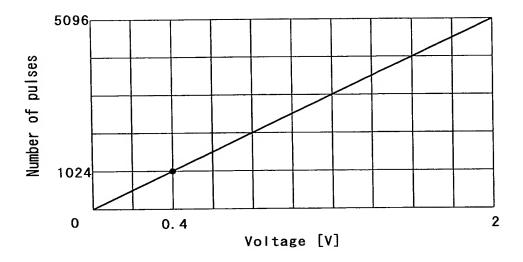


Fig. 38



TRACTION CONTROL SYSTEM AND SENSOR UNIT THEREOF HATTORI, Yutaka et al.

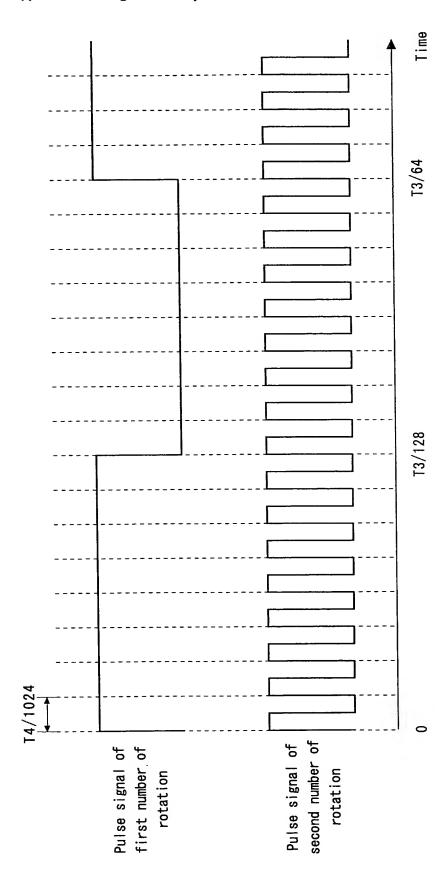


Fig. 39

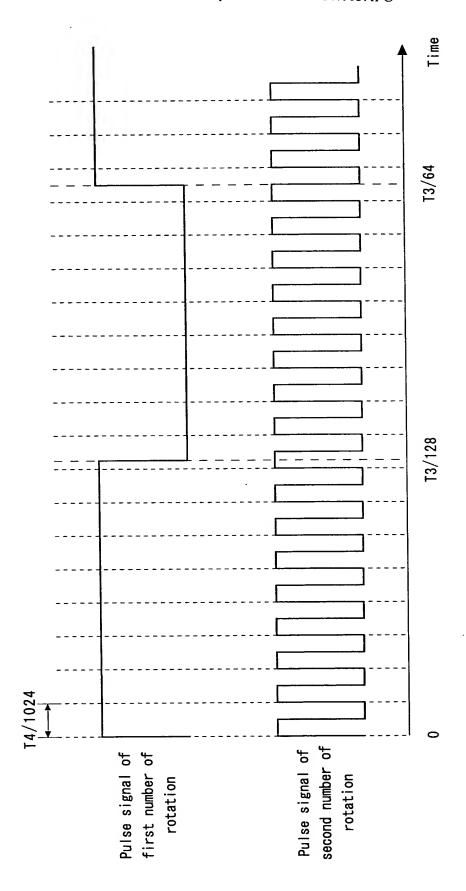


Fig. 40

TRACTION CONTROL SYSTEM AND SENSOR UNIT THEREOF HATTORI, Yutaka et al.

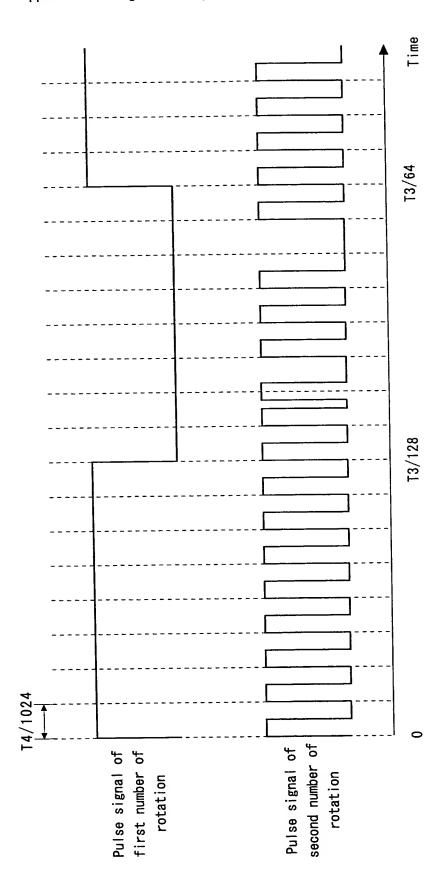
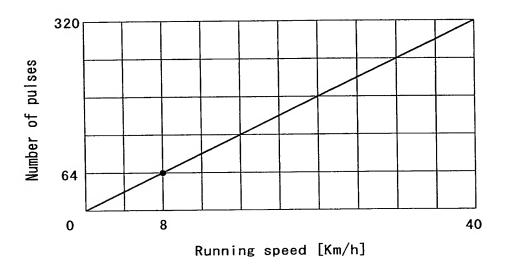


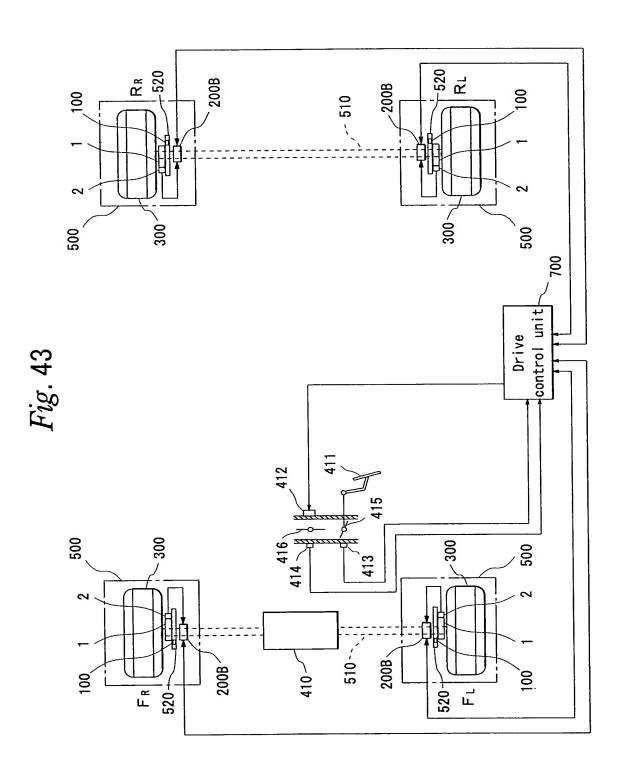
Fig 41

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Fig. 42





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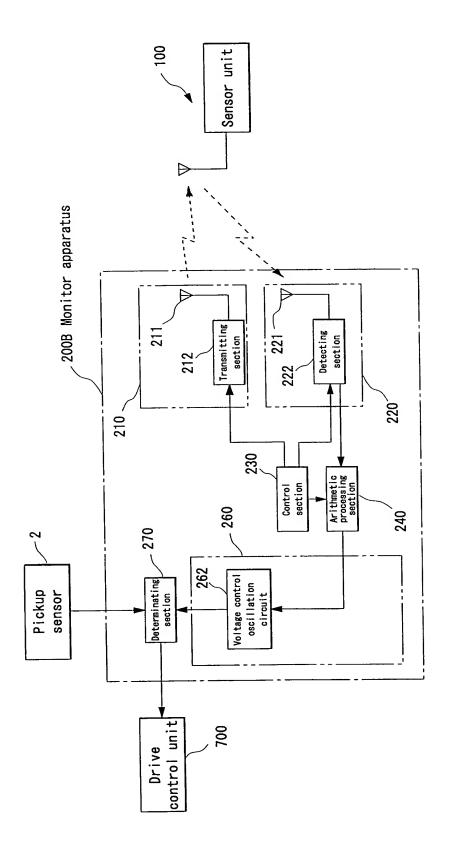


Fig. 44

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Fig. 45

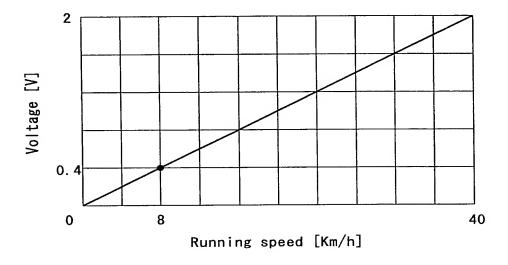


Fig. 46

